

JAYA GROUP OF INSTITUTIONS – THIRUNINRAVUR

4TH SEMESTER – B.E / B.Tech.

INTERNAL ASSESSMENT - II (MODEL EXAMINATION - II)

Sub.Name: **CONTROL SYSTEM ENGINEERING**

Date: **11/03/2015**

Sub.Code: **EC 6405**

Branch: **ECE**

Duration: **180 Minutes**

Max.Marks: **100**

PART – A (10X2=20) Answer all questions

1. What is frequency response?
2. What are frequency domain specifications?
3. Define gain margin.
4. Find type and order of the system, $G(s) = 1/[s^2(s+1)(s+2)]$.
5. What is Nichols plot?
6. Define stability.
7. What is Nyquist stability criterion?
8. Determine angle of asymptote and centroid.
9. What is dominant pole?
10. Construct routh array for the system, $s^2 + 2s + 3 = 0$.

PART – B (5X16=80) Answer the questions as per the choice

11(a). For the following transfer function draw bode plot and obtain gain cross-over frequency, $G(s) = 20/[s(1+3s)(1+4s)]$. (16)

Or

(b). Sketch bode plot for the following transfer function and determine the system gain K for the gain cross-over frequency 5 rad/sec, $G(s) = Ks^2 / [(1+0.2s)(1+0.02s)]$. (16)

12(a). The open loop transfer function of a unity feedback system is given by $G(s) = 1/[s(1+s)(1+2s)]$. Sketch the polar plot and determine the gain margin, phase margin. (16)

Or

(b). Consider a unity feedback system having an open loop transfer function, $G(s) = K/[s(1+0.5s)(1+4s)]$. Sketch the polar plot and determine the value of K so that (i) gain margin is 20db and (ii) phase margin is 30° . (16)

13(a). Derive the expressions for M and N circles.

(16)

Or

(b)(i). Construct routh array and determine the stability of the system whose characteristic equation is $s^6 + 2s^5 + 8s^4 + 12s^3 + 20s^2 + 16s + 16 = 0$. Also determine the number of roots lying on right half of s-plane, left half of s-plane and on imaginary axis.

(8)

(ii). By routh stability criterion determine the stability of the system represented by the characteristic equation, $9s^5 - 20s^4 + 10s^3 - s^2 - 9s - 10 = 0$. Comment on the location of roots of characteristic equation.

(8)

14(a). A unity feedback control system has an open loop transfer function, $G(s) = K/[s(s^2 + 4s + 13)]$. Sketch the root locus.

(16)

Or

(b). Sketch the root locus of the system whose open loop transfer function is, $G(s) = K/[s(s+2)(s+4)]$. Find the value of K so that the damping ratio of the closed loop system is 0.5.

(16)

15(a). Draw the Nyquist stability plot for the system whose open transfer function is, $G(s)H(s) = K/[s(s+2)(s+10)]$. Determine the range of K for which the closed loop system is stable.

(16)

Or

(b)(i). Determine Nyquist stability criterion for the closed loop system, whose open loop transfer function is given by, $G(s)H(s) = (s+2)/[(s+1)(s-1)]$.

(8)

(ii). Construct routh array and determine the stability of the system represented by the characteristic equation, $s^5 + 5s^4 + 2s^3 + 2s^2 + 3s + 5 = 0$.

(8)

ECE

4 marks